



# SNS COLLEGE OF TECHNOLOGY

(An Autonomous Institution)

Approved by AICTE, New Delhi, Affiliated to Anna University, Chennai

Accredited by NAAC-UGC with 'A++' Grade (Cycle III) &

Accredited by NBA (B.E - CSE, EEE, ECE, Mech & B.Tech.IT)

COIMBATORE-641 035, TAMIL NADU

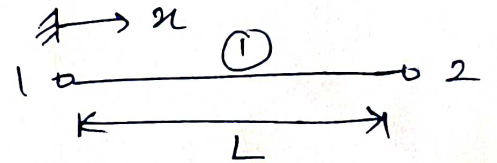


## DERIVATION (DISPLACEMENT FUNCTION) STEP FUNCTION

Faculty Name : **Dr.M.Subramanian,** Academic Year : **2024-2025 (Odd)**  
 Year & Branch : **III Aerospace** Semester : **V**  
 Course : **19ASB302 - Finite Element Method for Aerospace**

Trial function equation

$$u = a_0 + a_1 x$$



$$x=0$$

$$x=L$$

$$u = u_1$$

$$u = u_2$$

In matrix form,

$$u = \begin{bmatrix} 1 & x \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} \quad \text{--- (1)}$$

Apply Boundary condition BC  $\rightarrow$

$$u_1 = a_0 + a_1(0)$$

$$u_2 = a_0 + a_1 L$$

$$u_1 = a_0 \quad \text{--- (2)}$$

$$u_2 = a_0 + a_1 L \quad \text{--- (3)}$$

$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & L \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix}$$

$$\begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & L \end{bmatrix}^{-1} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}^{-1}$$

$$\begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \frac{1}{L} \begin{bmatrix} L & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \quad \text{--- (4)}$$

$$\text{(4)} \rightarrow \text{(1)}$$

$$U = \begin{bmatrix} 1 & x \end{bmatrix} \frac{1}{L} \begin{bmatrix} L & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

Prepared: Dr. M. Subramanian/Professor & Head Aerospace Engineering



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$$= \frac{1}{L} \begin{bmatrix} 1 & x \end{bmatrix} \begin{bmatrix} L & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$U = \frac{1}{L} \begin{bmatrix} L-x & x \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{L-x}{L} & \frac{x}{L} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$U = \frac{L-x}{L} u_1 + \frac{x}{L} u_2 = N_1 u_1 + N_2 u_2$$

$$N_1 = \frac{L-x}{L} \quad ; \quad N_2 = \frac{x}{L}$$

$$BC^1 \quad x=0 \quad (\text{Boundary condition})$$

$$N_1 = \frac{L-0}{L} = 1 \quad ; \quad N_2 = \frac{0}{L} = 0$$

$$BC^2 \quad x=L$$

$$N_1 = \frac{L-L}{L} = 0 \quad ; \quad N_2 = \frac{L}{L} = 1$$

$$= 0$$

$$= 1$$

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Shape function of 1-D linear bar element

$$U = N_1 u_1 + N_2 u_2$$

$$U = \left( \frac{L-x}{L} \right) u_1 + \left( \frac{x}{L} \right) u_2$$

Stiffness matrix 1D bar element.

$$[K] = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$[K][U] = [F] \longrightarrow \begin{matrix} \text{Load} \\ \text{displacement} \end{matrix}$$

Stress on element.

$$\sigma = E \cdot e$$

$$= E \cdot \frac{du}{dx} = E \frac{u_2 - u_1}{x}$$

Force vector / Load vector for 1-D

$$[F] = \frac{PAL}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Reaction force,

$$[R] = [K][U] - [F]$$

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